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Fairness-Oriented Resource Allocation for Energy Efficiency Optimization in Uplink OFDMA Networks

Hamza Umit Sokun, Ebrahim Bedeer, Ramy H. Gohary, and Halim Yanikomeroglu

Abstract—Due to the battery-limited nature of mobile devices, improving energy efficiency (EE) of individual users and ensuring EE fairness among those users are one of the key design issues in uplink transmission of cellular networks. In this paper, we consider the joint optimization of discrete power and resource blocks allocations to maximize the minimum EE among users subject to individual power budget constraints. The optimization problem is combinatorial. Thus, we propose an efficient algorithm, based on semidefinite relaxation with Gaussian randomization, to solve the resultant non-convex problem in polynomial time complexity. The numerical results show how well the proposed algorithm performs against the optimal one and indicate the impact of discrete power levels on the fairness-oriented EE optimization.

Index Terms—Energy efficiency, max-min fairness, OFDMA, convex optimization, semidefinite relaxation, randomization.

I. INTRODUCTION

Today’s mobile devices become an irreplaceable part of our life with a wide range of new emerging applications and services, e.g., GPS navigation, e-healthcare, and mobile video conference. However, these advance applications and services require not only higher data rates [1], but also higher energy consumption. Such a rise in energy consumption adversely affects the battery life of mobile devices that are typically powered by pre-charged batteries. To prolong the battery life of the devices, for all users, it is important to have the highest energy efficiency (EE) possible. However, this will lead to a problem of EE fairness (balancing) among users, particularly in uplink transmissions, as each individual will want to maximize their own benefits. Hence, for current and next-generation wireless networks, not only improving users’ EE, but also ensuring EE fairness among users are critically important design requirements.

Generally speaking, for improving the users’ EE, their data rate needs to be increased, while at the same time, their energy consumption needs to be decreased. To achieve these objectives, resource allocation is an effective tool [2]. More specifically, optimizing the way how the available resource blocks (RBs) in the network are allocated among the users, and the way how the users allocate their available power across those RBs

can substantially enhance the users’ EE [3]. For further enhancement in the users’ EE, the interaction between these network functionalities should be considered.

A. Prior Work and Contribution

Despite the rich literature on the overall EE optimization in the downlink of an orthogonal frequency division multiple access (OFDMA)-based systems, fairness-oriented individual EE optimization in the uplink of OFDMA-based systems is not thoroughly investigated from resource allocation perspective. There are only a limited number of works in the literature studied this problem (see, e.g., [4]–[7]). In [4], the power optimization problem with fixed RB allocation is considered for uplink transmission in OFDMA systems to maximize the minimum EE of all users. Similarly, in [5], the power optimization problem is discussed for uplink transmission in spectrum-sharing networks to achieve the proportional, harmonic, and max-min fair EE. On the other hand, the problem of the joint optimization of subcarrier and power allocation is addressed in [6] to achieve the max-min EE fairness in the uplink transmission of OFDMA networks. Lastly, in [7], the problem of the joint optimization of subcarrier and power allocation is investigated to attain the max-min EE fairness in the uplink transmission of amplify-and-forward cooperative OFDMA networks. However, it is important to mention that the resource allocation techniques proposed in [4]–[7] are based on continuous power allocation, rather than allocation of discrete power levels. Hence, implementing such resource allocation techniques in practical networks supporting discrete power levels, e.g., LTE networks, can be problematic.

In this work, we propose a joint resource allocation technique to maximize the minimum EE of all users in OFDMA networks, while taking practical implementation constraints into account, i.e., including discrete power levels and per-user power budget. In particular, we consider the joint design of RB and discrete power allocations, and formulate the joint design as a max-min EE optimization problem. Restricting the power levels for being discrete has several advantages, such as simplifying the hardware designs, and enabling a low

cost implementation, however, this usually leads to non-convex formulations. To overcome this difficulty, we consider the semidefinite relaxation (SDR)-based Gaussian randomization technique that invokes a relaxation on the rank of the matrix-value optimization variable to obtain near-optimal results in polynomial time.

II. PROBLEM STATEMENT AND PRELIMINARIES

This section describes the network model under consideration, and discusses the optimization problem formulation.

A. System Description

We consider an uplink OFDMA network which consists of a base station (BS), M users, J RBs and L discrete power levels. Let $\mathcal{M} = \{1, \dots, M\}$ denote the set of users, $\mathcal{J} = \{1, \dots, J\}$ denote the set of RBs and $\mathcal{P} = \{p^1, \dots, p^\ell, \dots, p^L\}$ denote the set of power levels, where $L = |\mathcal{P}|$ is the cardinality of \mathcal{P} . Let h_m^j represent the channel gain for the m -th user on the j -th RB. Then, the maximum achievable rate for m -th user on the j -th RB when ℓ -th power level is used can be expressed as

$$r_m^{j\ell} = B \log_2 \left(1 + \frac{p^\ell |g_m^j|^2}{BN_0} \right), \quad (1)$$

where each RB has a bandwidth of B and N_0 is the power spectral density of additive white Gaussian noise. Additionally, let binary variable $x_m^{j\ell}$ be an indicator variable that indicates whether the m -th user is associated with the BS on the j -th RB using the ℓ -th power level or not. Using the indicator variables, the overall transmission rate for the m -th user can be cast as $\sum_{j \in \mathcal{J}} \sum_{\ell \in \mathcal{P}} r_m^{j\ell} x_m^{j\ell}$. Moreover, to avoid interference among RBs, each RB is allocated to a single user at most, so that total usage of the j -th RB over the network should satisfy

$$\sum_{m \in \mathcal{M}} \sum_{\ell \in \mathcal{P}} x_m^{j\ell} \leq 1, \quad \forall j \in \mathcal{J}. \quad (2)$$

Energy Efficiency Metric: The power consumption for the m -th user is composed of two components. The first is the total transmit power consumption for m -th user to the BS, which can be expressed as $\sum_{j \in \mathcal{J}} \sum_{\ell \in \mathcal{P}} p^\ell x_m^{j\ell}$. Noting that in practice, this consumption is limited by a threshold, P_m^{\max} , so that it should satisfy

$$\sum_{j \in \mathcal{J}} \sum_{\ell \in \mathcal{P}} p^\ell x_m^{j\ell} \leq P_m^{\max}, \quad \forall m \in \mathcal{M}. \quad (3)$$

The second is circuitry power consumption for the m -th user to the BS, $P_{m,C}$. As a result, the overall power consumption at the m -th user

$$P_{m,T} = P_{m,C} + \frac{1}{\rho} \sum_{j \in \mathcal{J}} \sum_{\ell \in \mathcal{P}} p^\ell x_m^{j\ell}, \quad \forall m \in \mathcal{M}, \quad (4)$$

where ρ is the power amplifier efficiency constant.

The EE for each user is defined as the ratio between the total data rate and the total consumed power:

$$\mathcal{E}_{m,EE} = \frac{\sum_{j \in \mathcal{J}} \sum_{\ell \in \mathcal{P}} r_m^{j\ell} x_m^{j\ell}}{P_{m,T}} \text{ bits/Joule}, \quad \forall m \in \mathcal{M}. \quad (5)$$

Fairness Metric: For measuring the EE fairness between the users with the battery operated devices, we adopt a (non-numeric) qualitative metric, i.e., max-min fairness index. When the network reaches max-min EE fairness, any user's EE cannot be increased without decreasing another user's EE.

B. Problem Formulation for Fairness-Oriented Energy Efficiency Optimization

We consider RB and power allocations jointly to obtain a max-min energy-efficient resource allocation strategy in the uplink OFDMA networks. In particular, this strategy aims to maximize the minimum EE among all users while guaranteeing the total transmit power per user is not exceeded. We formulate the max-min optimization problem as follows:

$$\max_{\{x_m^{j\ell}\}} \min_{m \in \mathcal{M}} \mathcal{E}_{m,EE} = \frac{\sum_{j \in \mathcal{J}} \sum_{\ell \in \mathcal{P}} r_m^{j\ell} x_m^{j\ell}}{\frac{1}{\rho} \sum_{j \in \mathcal{J}} \sum_{\ell \in \mathcal{P}} p^\ell x_m^{j\ell} + P_{m,C}}, \quad (6a)$$

$$\text{subject to} \quad \sum_{m \in \mathcal{M}} \sum_{\ell \in \mathcal{P}} x_m^{j\ell} \leq 1, \quad \forall j \in \mathcal{J}, \quad (6b)$$

$$\sum_{j \in \mathcal{J}} \sum_{\ell \in \mathcal{P}} p^\ell x_m^{j\ell} \leq P_m^{\max}, \quad \forall m \in \mathcal{M}, \quad (6c)$$

$$x_m^{j\ell} \in \{0, 1\}, \quad \forall m \in \mathcal{M}, \forall j \in \mathcal{J}, \forall \ell \in \mathcal{P}. \quad (6d)$$

Noting that the objective is fractional, and the constraint in (6d) is non-convex. Hence, the optimization problem in (6) is a fractional integer non-linear programming problem. Finding out the optimal solution for such a non-convex problem requires exponential complexity and is computationally prohibitive. Hence, we propose a two-steps polynomial-time algorithm that based on the SDR technique with Gaussian randomization [8] to provide an approximate solution with high accuracy. In the next section, we will elaborate on the proposed algorithm.

III. PROPOSED SOLUTION

The idea behind the SDR technique¹ is that the original non-convex problem is first reformulated in a higher dimension, and next, the non-convex constraints are relaxed. The resulting convex problem is lastly used to approximate the original one. To facilitate formulating

¹A somewhat similar technique is used in [9] to address a different optimization problem in a different context. More specifically, in [9], maximizing the network-side overall EE is discussed in downlink of OFDMA-based systems, whereas herein the design objective is to improve minimum individual EE as much as possible in uplink of OFDMA-based systems.

the optimization problem in a higher dimension, we define the following five 3-dimensional tensors: \mathbf{A}_j , \mathbf{B}_m , \mathbf{G}_m , and \mathbf{X} . These tensors are in the form of a $J \times ML$ block-partitioned matrix with $1 \times M$ blocks, each with $J \times L$ entries. The tensor \mathbf{X} can be expressed as $\mathbf{X} = [\mathbf{X}_1 \ \dots \ \mathbf{X}_M]$, where, for all $m = 1, \dots, M$,

$$\mathbf{X}_m \text{ is given as } \mathbf{X}_m = \begin{bmatrix} x_m^{11} & \dots & x_m^{1\ell} \\ \vdots & \ddots & \vdots \\ x_m^{J1} & \dots & x_m^{JL} \end{bmatrix}. \text{ The tensor}$$

\mathbf{A}_j can be given as $\mathbf{A}_j = [\mathbf{A}_{j_1} \ \dots \ \mathbf{A}_{j_M}]$, $j = 1, \dots, J$, where for all $m = 1, \dots, M$, $\mathbf{A}_{j_m} = e_j \mathbf{1}_L^T$, where e_j is the j -th column of the $J \times J$ identity matrix \mathbf{I}_J . The tensor \mathbf{B}_m can be written as $\mathbf{B}_m = [\mathbf{B}_{m_1} \ \dots \ \mathbf{B}_{m_{\hat{m}}} \ \dots \ \mathbf{B}_{m_M}]$, $m = 1, \dots, M$, where for $i = 1, \dots, M$, $\mathbf{B}_{m_i} = \mathbf{0}_{J \times L}$ when $i \neq \hat{m}$, and, when $i = \hat{m}$, $\mathbf{B}_{m_{\hat{m}}} =$

$$\begin{bmatrix} r_{\hat{m}}^{11} & \dots & r_{\hat{m}}^{1\ell} \\ \vdots & \ddots & \vdots \\ r_{\hat{m}}^{J1} & \dots & r_{\hat{m}}^{JL} \end{bmatrix}. \text{ The tensor } \mathbf{G}_m \text{ can be expressed}$$

as $\mathbf{G}_m = [\mathbf{G}_{m_1} \ \dots \ \mathbf{G}_{m_{\hat{m}}} \ \dots \ \mathbf{G}_{m_M}]$, $m = 1, \dots, M$, where for $i = 1, \dots, M$, $\mathbf{G}_{m_i} = \mathbf{0}_{J \times L}$ when

$$i \neq \hat{m}, \text{ and, when } i = \hat{m}, \mathbf{G}_{m_{\hat{m}}} = \begin{bmatrix} p^1 & \dots & p^L \\ \vdots & \ddots & \vdots \\ p^1 & \dots & p^L \end{bmatrix}.$$

Subsequently, we obtain the following vectors: $\mathbf{x} \triangleq \text{vec}(\mathbf{X}^T)$, $\mathbf{a}_j \triangleq \text{vec}(\mathbf{A}_j^T)$, $\mathbf{b}_m \triangleq \text{vec}(\mathbf{B}_m^T)$, and $\mathbf{g}_m \triangleq \text{vec}(\mathbf{G}_m^T)$. Additionally, we introduce the vector $\mathbf{x} \in \{0, 1\}^{MJL}$. Using the defined vectors, the optimization problem can be cast as

$$\max_{\mathbf{x}} \min_{m \in \mathcal{M}} \frac{\mathbf{b}_m^T \mathbf{x}}{\frac{1}{\rho} \mathbf{g}_m^T \mathbf{x} + P_{m,C}}, \quad (7a)$$

$$\text{subject to } \mathbf{a}_j^T \mathbf{x} \leq 1, \quad \forall j \in \mathcal{J}, \quad (7b)$$

$$\mathbf{g}_m^T \mathbf{x} \leq P_m^{\max}, \quad \forall m \in \mathcal{M}, \quad (7c)$$

$$\mathbf{x} \in \{0, 1\}^{MJL}. \quad (7d)$$

Using the vector $\mathbf{y} \in \{-1, 1\}^{MJL}$, where $\mathbf{y} = 2\mathbf{x} - \mathbf{1}$, we reformulate the problem in (6) as

$$\max_{\mathbf{y}} \min_{m \in \mathcal{M}} \frac{\mathbf{b}_m^T (\mathbf{y} + \mathbf{1})}{\frac{1}{\rho} \mathbf{g}_m^T (\mathbf{y} + \mathbf{1}) + 2P_{m,C}}, \quad (8a)$$

$$\text{subject to } \frac{1}{2} \mathbf{a}_j^T (\mathbf{y} + \mathbf{1}) \leq 1, \quad \forall j \in \mathcal{J}, \quad (8b)$$

$$\frac{1}{2} \mathbf{g}_m^T (\mathbf{y} + \mathbf{1}) \leq P_m^{\max}, \quad \forall m \in \mathcal{M}, \quad (8c)$$

$$\mathbf{y} \in \{-1, 1\}^{MJL}. \quad (8d)$$

It is worth to mention that the constraints in (8b) and (8c) are linear. However, since the objective (8a) and the constraint (8d) are non-convex, the problem in (8) is still non-convex.

The next step for applying the SDR technique is to formulate the optimization problem of (8) in a

higher dimension, i.e., the optimization variables are replaced with symmetric positive semidefinite (PSD) matrices [8]. Before proceeding with the next step, we also define the following vectors in \mathbb{R}^{MJL+1} , $\hat{\mathbf{g}}_m \triangleq [\frac{1}{\rho} \mathbf{g}_m^T \ \frac{1}{\rho} \mathbf{g}_m^T \mathbf{1} + 2P_{m,C}]^T$, $\hat{\mathbf{a}}_j \triangleq [\mathbf{a}_j^T \ \mathbf{a}_j^T \mathbf{1}]^T$, $j = 1, \dots, J$, $\hat{\mathbf{b}}_m \triangleq [\mathbf{b}_m^T \ \mathbf{b}_m^T \mathbf{1}]^T$, $m = 1, \dots, M$, $\hat{\mathbf{1}} \triangleq [\mathbf{1}^T \ \mathbf{1}^T \mathbf{1}]^T$, $\hat{\mathbf{y}} \triangleq [\mathbf{y}^T \ \mathbf{1}]^T$ and $\hat{\mathbf{f}} \triangleq [\mathbf{0}^T \ \mathbf{1}]^T$. Subsequently, we define the following $(MJL+1) \times (MJL+1)$ matrices $\mathbf{K}_{\hat{\mathbf{a}}_j} \triangleq \hat{\mathbf{f}} \hat{\mathbf{a}}_j^T$, $\mathbf{K}_{\hat{\mathbf{g}}_m} \triangleq \hat{\mathbf{f}} \hat{\mathbf{g}}_m^T$, and $\mathbf{K}_{\hat{\mathbf{b}}_m} \triangleq \hat{\mathbf{f}} \hat{\mathbf{b}}_m^T$. In addition, we define the symmetric matrices $\mathbf{Y} \in \mathbb{R}^{MJL \times MJL}$ and $\mathbf{\Omega} \in \mathbb{R}^{(MJL+1) \times (MJL+1)}$ to be $\mathbf{Y} \triangleq \mathbf{y} \mathbf{y}^T$ and $\mathbf{\Omega} = \hat{\mathbf{y}} \hat{\mathbf{y}}^T$, in particular, $\mathbf{\Omega} = \begin{bmatrix} \mathbf{Y} & \mathbf{y} \\ \mathbf{y}^T & 1 \end{bmatrix}$. Using those matrices, the optimization problem in (8) can be cast as

$$\max_{\mathbf{\Omega}} \min_{m \in \mathcal{M}} \frac{\text{Tr}(\mathbf{K}_{\hat{\mathbf{b}}_m} \mathbf{\Omega})}{\text{Tr}(\mathbf{K}_{\hat{\mathbf{g}}_m} \mathbf{\Omega})}, \quad (9a)$$

$$\text{subject to } \frac{1}{2} \text{Tr}(\mathbf{K}_{\hat{\mathbf{a}}_j} \mathbf{\Omega}) \leq 1, \quad \forall j \in \mathcal{J}, \quad (9b)$$

$$\frac{1}{2} \text{Tr}(\mathbf{K}_{\hat{\mathbf{g}}_m} \mathbf{\Omega}) \leq \frac{1}{\rho} P_m^{\max} + P_{m,C}, \quad \forall m \in \mathcal{M}, \quad (9c)$$

$$\mathbf{\Omega} \succeq \mathbf{0}, \quad (9d)$$

$$\text{diag}(\mathbf{\Omega}) = \mathbf{1}, \quad (9e)$$

$$\text{rank}(\mathbf{\Omega}) = 1. \quad (9f)$$

This formulation is non-convex due to both the objective function (9a) and the rank-1 constraint (9f). However, noting that after dropping rank-1 constraint, the resulting problem is quasi-convex [10], which can be efficiently tackled using the bisection method. Using a new variable, \mathcal{E}_0 , we reformulate the relaxed problem as

$$\max_{\mathcal{E}_0, \mathbf{\Omega}} \mathcal{E}_0, \quad (10a)$$

$$\text{subject to } \text{Tr}(\mathcal{E}_0(\mathbf{K}_{\hat{\mathbf{g}}_m} - \mathbf{K}_{\hat{\mathbf{b}}_m}) \mathbf{\Omega}) \leq 0, \quad \forall m \in \mathcal{M}, \quad (10b)$$

$$(9b) - (9e). \quad (10c)$$

To obtain the maximum value of \mathcal{E}_0 , we solve a series of convex feasibility problems, each of which is of the form

$$\text{find } \mathbf{\Omega}, \quad (11a)$$

$$\text{subject to } \text{Tr}(\mathcal{E}_0(\mathbf{K}_{\hat{\mathbf{g}}_m} - \mathbf{K}_{\hat{\mathbf{b}}_m}) \mathbf{\Omega}) \leq 0, \quad \forall m \in \mathcal{M}, \quad (11b)$$

$$(9b) - (9e), \quad (11c)$$

where \mathcal{E}_0 is fixed at each iteration of the bisection method and it lies in $[0, \mathcal{E}_{\max}]$, where $\mathcal{E}_{\max} = \min_{m \in \mathcal{M}} (\frac{b_m^T \mathbf{1}}{P_{m,C}})$. Let $\mathbf{\Omega}^*$ represent the optimal solution of (10) corresponding to the optimal value of \mathcal{E}_0 . If $\mathbf{\Omega}^*$ has a rank one, the relaxation is tight. Otherwise, we use Gaussian randomization [8] in order to obtain an approximate solution. The idea behind of the Gaussian randomization technique

is to tackle a stochastic version of the deterministic problem in (10). Particular, in this technique, several random samples, T , are first generated from a multivariate Gaussian distribution with the covariance matrix of Ω^* . Then, the random vector that maximizes the objective in (6) is selected as the sub-optimal solution.

The SDR-based Gaussian randomization technique is summarized in Algorithm 1.

Algorithm 1: SDR-based Gaussian randomization

Input: T, ρ, P_m^{\max} , and $P_{m,c}, m \in \mathcal{M}$.

Output: \mathbf{x}^* .

- 1 **Relax the non-convex problem:** Drop the rank-1 constraint.
 - 2 **Solve the semidefinite relaxation problem:** Obtain the optimal solution of the relaxed problem.
 - 3 **for** $t = 1 : T$ **do**
 - 4 **Generate a random vector sample:** Obtain a random vector drawn from the Gaussian distribution.
 - 5 **Find the candidate binary solution:** Quantize entries of the realization, and obtain the candidate solution.
 - 6 **Determine the feasibility of the candidate solution:** Check the constraints.
 - 7 **if satisfied then**
 - 8 | Record.
 - 9 **Find the best solution:** Select the best among the feasible solutions, which has the highest objective function value and assign it to \mathbf{x}^* .
-

A. Complexity Discussion

The proposed algorithm uses the bisection method to solve the problem in (10). This method requires $\log_2(\mathcal{E}_{\max}/\kappa)$ number of iterations for the convergence, where $\kappa > 0$ is the solution accuracy. Each iteration involves solving a convex PSD-constrained problem, with the computational complexity of $\mathcal{O}((MJJ)^{3.5})$ [8]. Finally, it uses the Gaussian randomization technique. At this step, the complexity of generating T random samples for which the objective is evaluated is $\mathcal{O}((MJJ)^2T)$ [8]. Therefore, the total computational complexity can be found as $\mathcal{O}((MJJ)^{3.5} \log_2(\mathcal{E}_{\max}/\kappa) + (MJJ)^2T)$. Even though the proposed centralized algorithm has polynomial-time complexity, the order of the polynomial complexity is relatively high. Hence, it is applicable in small-to-medium-size networks. For large-size networks, decentralized algorithms can be more desirable in order to ensure reduced complexity and overhead. However, we have the following remarks:

- One of the most effective means of developing optimization-based decentralized designs is to begin with a centralized design and then, using Lagrangian duality, the formulation is decoupled to facilitate the task of each node in the network to optimize its parameters locally. In other words, centralized

formulations are usually useful in developing decentralized ones.

- A decentralized formulation can be regarded as a centralized one, but with decoupling constraints. This implies that the solutions generated through the centralized formulation constitute an upper bound on the solutions generated through their decentralized counterparts. In other words, the centralized formulations developed in our work will not only serve as starting points for developing effective decentralized algorithms, but also to serve a benchmark for validating and examining their efficacy.

IV. SIMULATION RESULTS

In this section, the EE performance of the proposed resource allocation scheme in an OFDMA network is evaluated with simulations. We assume that the path loss model is expressed as $128.1 + 37.6 \log_{10}(d)$ for the user-to-BS links [11], where d denotes the distance in kilometers. The log-normal distribution with a standard deviation of 8 dB is used to model the shadowing factor. The power-level set consists of L equally located points in $[0.05P_m^{\max}, 0.5P_m^{\max}]$, and $P_m^{\max} = P^{\max}, \forall m \in \mathcal{M}$, unless otherwise stated. Furthermore, we assume that noise power spectral density is -174 dBm/Hz, the bandwidth of each RB is 180 kHz, and the power amplifier efficiency is 38%. We use 100 Monte Carlo simulations to obtain the average performance. The optimization problem is solved using the SDPT3 package [12] and the randomization technique is implemented using 1000 independent randomization samples.

Fig. 1 considers a network with 4 RBs, 3 users, 2 power levels. In this network, we assume that the static circuitry power consumption is 25 dBm. In Fig. 1, the performance of proposed scheme is compared against the optimal solution derived through exhaustive search. From this figure, it can be readily observed that the performance of the proposed technique is close to the optimal one, especially at high values of the transmit power. For instance, at the transmit power of 31 dBm, the gap between the minimum EE and the one generated by the SDR-technique is 2.97×10^4 bits/Joule, which is about 1% of the objective value obtained by exhaustive search. Moreover, for completeness of presentation, a comparison of these two algorithms in terms of EE fairness is given in Fig. 2. For quantifying the EE fairness among multiple users, we adopt Jain's fairness index [13].² Since the adopted EE optimization metric, viz., max-min fair EE,

²Jain's index is widely used as a (numeric) quantitative fairness metric; a higher value of Jain's index corresponds to a fairer rate allocation. Particularly, it is defined as $F(\mathbf{x}) = \frac{(\sum_{m \in \mathcal{M}} \sum_{j \in \mathcal{J}} \sum_{\ell \in \mathcal{P}} r_m^{j\ell} x_m^{j\ell})^2}{M \sum_{m \in \mathcal{M}} (\sum_{j \in \mathcal{J}} \sum_{\ell \in \mathcal{P}} r_m^{j\ell} x_m^{j\ell})^2}$. It is a continuous non-convex function, $F(\mathbf{x}) : \mathbb{R}_m^+ \rightarrow \mathbb{R}^+$, with values in the interval $[\frac{1}{M}, 1]$.

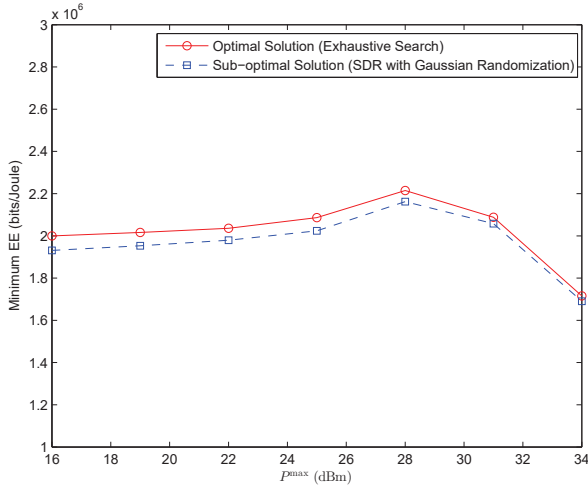


Fig. 1. Performance of the proposed sub-optimal technique against the optimal one.

improves EE fairness between different users as much as possible, as expected, the achieved EE Jain's fairness index is high, specifically, higher than 0.9 for all values of the transmit power.

Fig. 3 considers a network with 10 RBs, 5 users, and the different number of power levels, i.e., 2, 4, and 8. In this network, we assume that the static circuitry power consumption is 25 dBm. Fig. 2 demonstrates the impact of the number of power levels on the average network performance. One can see that for a specific transmit power, the minimum EE enhances as the number of power level raises. This is due to the fact that the increase of the number of power level provides extra degrees of freedom in the energy-efficient resource allocation optimization. Another important observation is that the impact of the number of power levels on max-min EE optimization becomes less significant as the transmit power increases.

Lastly, Fig. 4 considers a network with 8 RBs, 4 users. In this network, we assume that the static circuitry power consumption is 25 dBm, and the number of power levels varies from 1 to 11. Fig. 4 reveals the average computational time required by the proposed algorithm. From this figure, it can be observed that the proposed algorithm requires a polynomial amount of computational time.

V. CONCLUSION

In this work, we addressed the problem of optimizing resource allocation in uplink OFDMA networks for providing the EE fairness among the users while considering discrete power levels. Particularly, we focused on how to maximize the minimum user EE in the network by jointly optimizing RB and discrete power allocation. We first formulated the optimization problem, but unfortunately, the resulting formulation was not

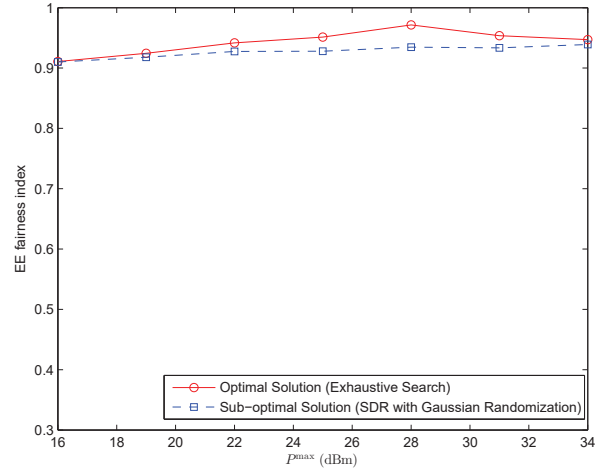


Fig. 2. EE fairness among the users.

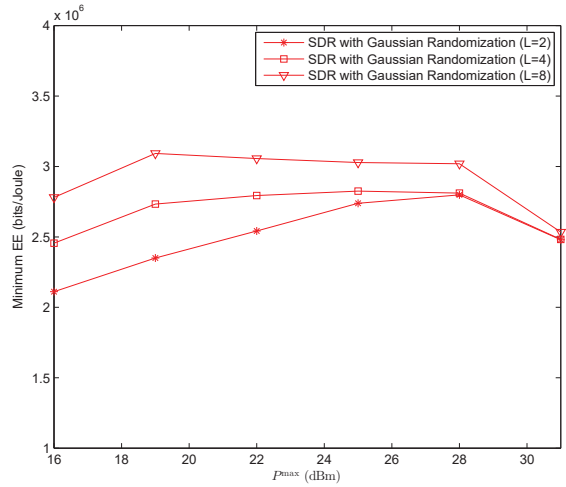


Fig. 3. Performance of the proposed technique with the different number of power levels.

convex. In order to tackle this difficulty, we proposed an SDR-based technique with polynomial time complexity that approximates the solution for the max-min EE problem using a convex program. The numerical results indicated that the proposed technique does not only achieve the desirable improvement on the users' EE, but also ensures EE fairness among the users. As future works, we plan to put emphasis on distribute solutions, and to investigate the joint optimization of user association, RBs and discrete power allocations for the EE maximization in interference-limited OFDMA-based networks.

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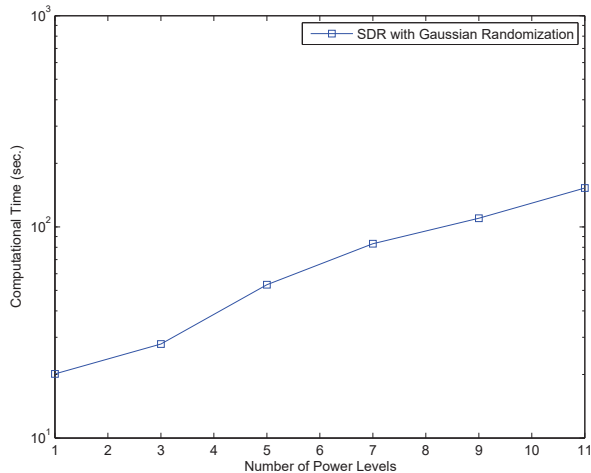


Fig. 4. Computational time versus network size.

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